# World Geospatial Forum - Rotterdam, Netherlands 2023

#### **Steven McArdle**

Jian Yang Lamiae El Mendili Yasmin Khayer Hans Lie-Nielsen Aleksey Naumov

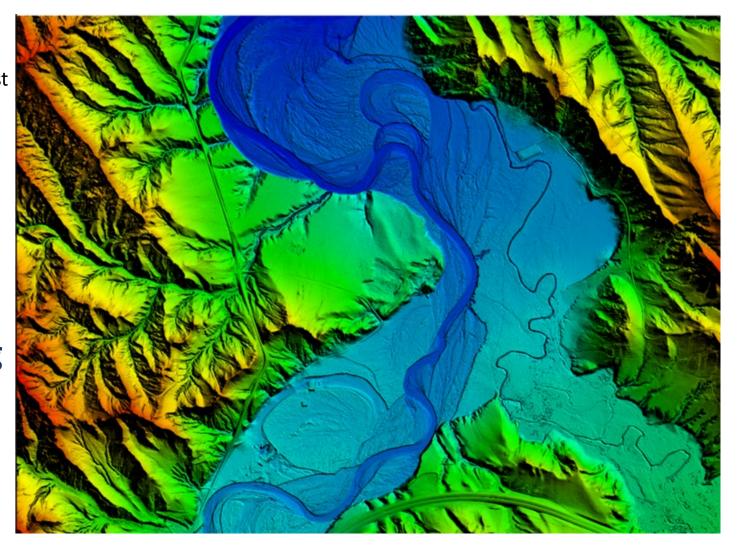
#### **Chief Innovation Officer**

Remote Sensing Specialist
Artificial Intelligence Specialist
Geospatial Data Engineer
Remote Sensing Specialist
Environmental Scientist

**VeriDaaS Corporation Denver - Calgary - Toronto - Bangalore** 

Application of Geiger Mode
LiDAR Technology for Extracting
Forest Attributes and Terrain
Mapping

smcardle@veridaas.com



#### Introduction

- Introduction to Geiger Mode LiDAR (GML) technology
- Visual example of Geiger Mode LiDAR data
- Discussion on the extraction of forest attributes and terrain mapping
- Deep Learning Model
- Summary

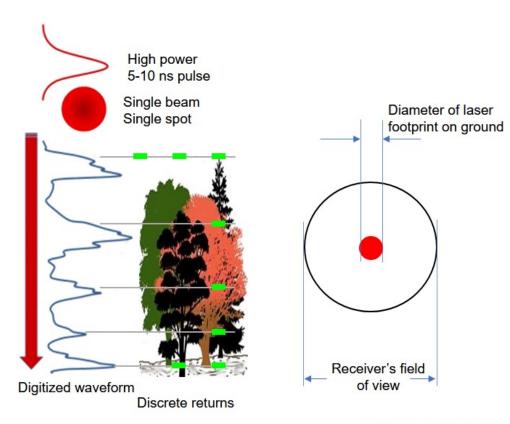


# **Introduction Geiger Mode LiDAR**

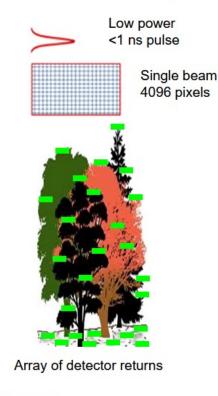
#### Receiving Photon Sensor Geiger Mode Avalanche Photodiode Detectors (GmAPD) Counter Arm **Physical Sensor** 128 x 32 = 4,096 detectors **Receiving Photons High-Speed Clock** Transmitted Laser Pulse **Scattering Photons** Counts Time of Flight Accumulated to Surface Timing Counts -Geiger Mode LiDAR, is a photon base sensors 25 Pulses Detection that measures the Time of Flight (TOF) of Threshold reflected photons from a laser pulse to determine a range (a distance from aircraft to ground) Timing/Range Bins

# **Receiving Photons**

#### Convention Linear Mode LiDAR



# Geiger-mode LiDAR (a 3D Camera)



Diameter of laser Illuminates entire receiver's FOV

Geiger mode APD array

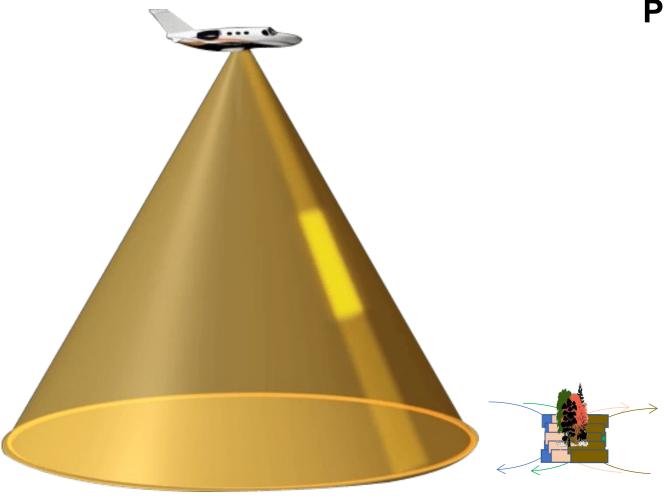
Spot Size at Ground Level

Spot size Linear LiDAR @ 4,300 AGL' and Geiger Mode @ 12,000' MSL



VeriDaaS Geiger-mode LiDAR
35 μrad
13 cm

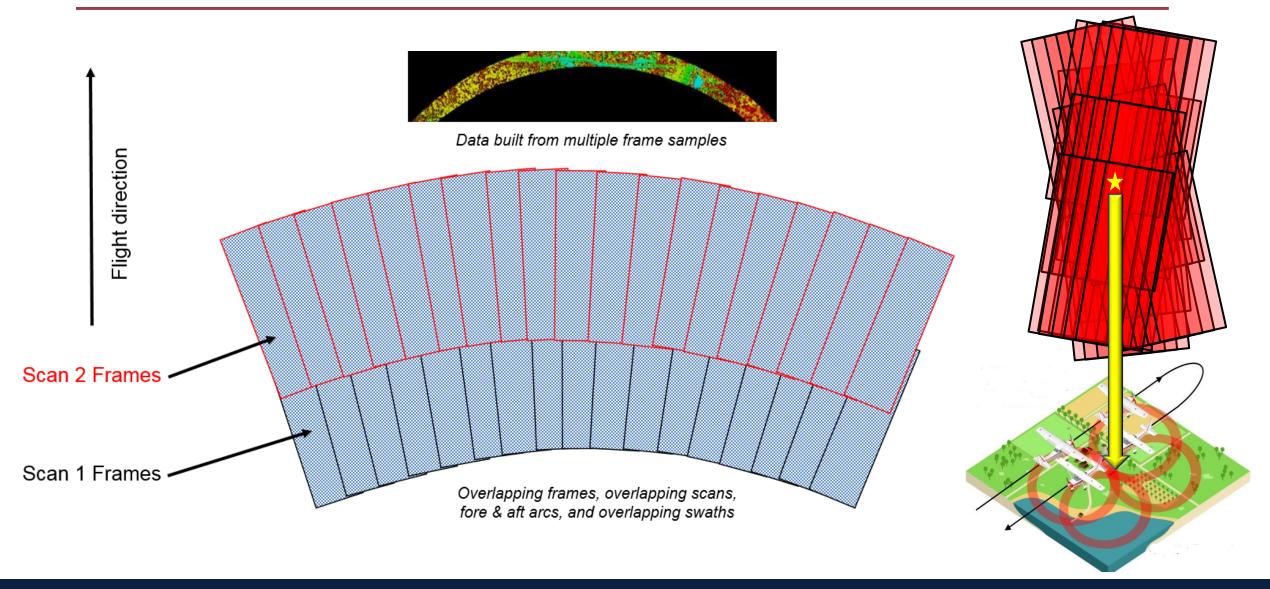
#### **Introduction Geiger Mode LiDAR**



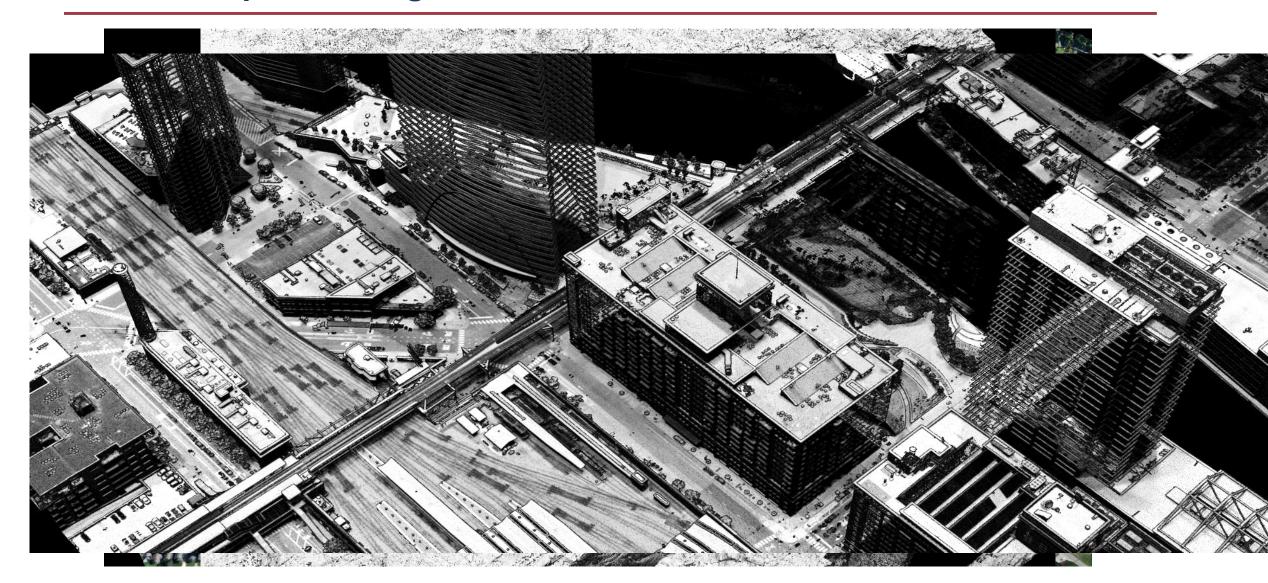
#### Palmer Scanner & Look diversity

- 4,096 measurements per laser flash or for each frame
- 50,000 flashes per second creating overlapping frames
  - (Approximately 205 million elevation measurement per second)
- Rotating Palmer Scanner Creates Overlaps in Flight Direction of frames in direction of the Flight path
- Forward and Aft Looks for Each Rotation of Scanner at 15° angle

# **Introduction Geiger Mode LiDAR**



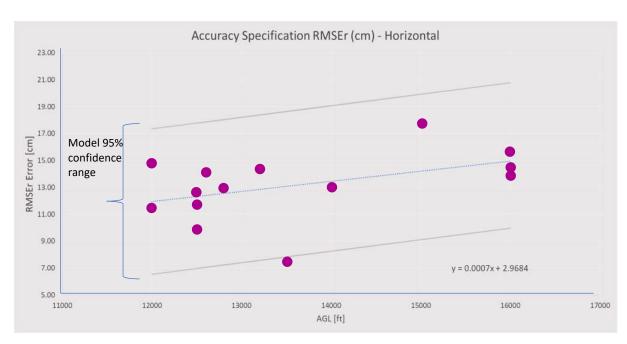
# **Visual Examples of Geiger Mode LiDAR Data**

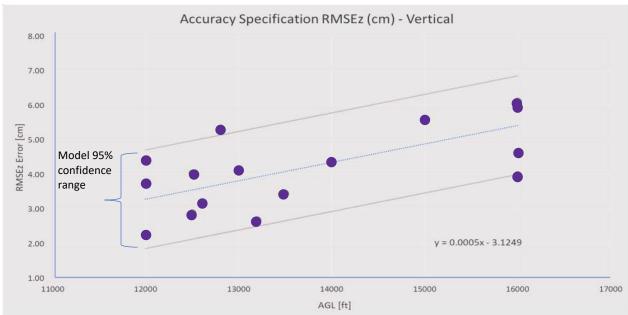




# **Accuracy**

#### Actual horizontal and vertical accuracy results are displayed below from project collections





Mean/STDEV Horizontal Accuracy (RMSEr)
13.4cm +/- 2.6cm from 15 projects

Mean/STDEV Vertical Accuracy (RMSEz)
4.3 cm +/-1.2cm from 19 projects

Accuracy – Multi-Project Empirical RMSE values

VeriDaaS has collected over 520,000 km<sup>2</sup>



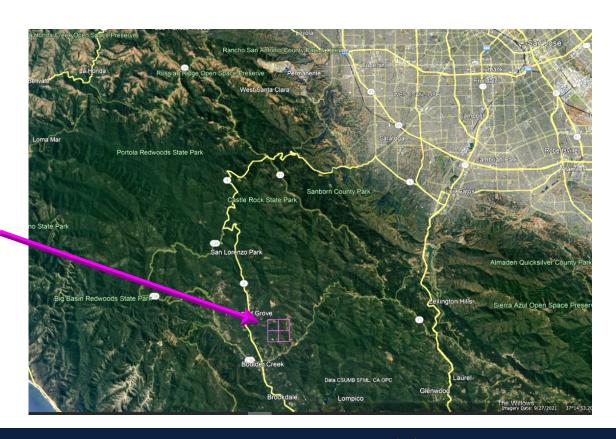
#### **Extracting Forestry Attribute and Terrain Mapping**

Geiger Mode LiDAR data is well suite for applications related to forestry/tree attributes and under canopy terrain mapping to support for the following reasons:

- Narrow pixel size to acquire terrain measurements through the gaps of the tree.
- Ultra high data density up to 140 ppms
- Multi-look angle for optimizing structural mapping
- Uniform data distribution
- Accurate data

Forestry Use Case Boulder Creek in Redwood Forest area of California

- Forest/tree area delineation.
- Tree top location
- Crown delineation



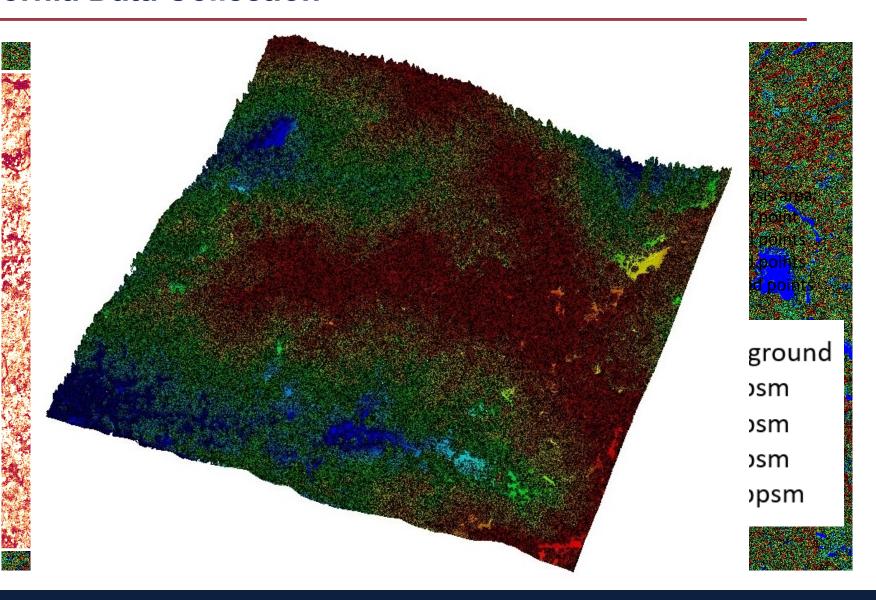


#### **Boulder Creek California Data Collection**

#### **Collection Details**

- May 2021
- ~ 50 ppms
- Acquisition 12,800ft AGL (3.9km AGL)
- 50+ % overlap
- 27° Field of View

Example area is 1 sq mile (2.6 km<sup>2</sup>)



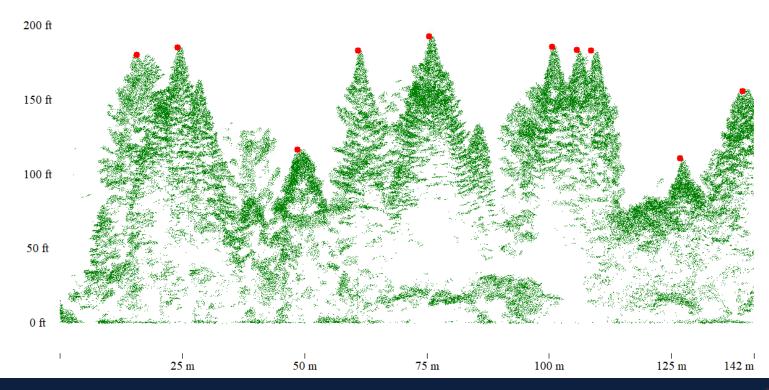


# **Forestry Attributes**

- Tree height Above Ground Level (AGL)
- Forest/tree area delineation
- Individual tree top detection
- Individual tree crown segmentation

Tree density distribution
Tree height distribution
Tree lean
Tree volume

Biomass/Carbon Quantification
Fallen Tree Risk
Timber Yield
Vegetation Encroachment
Forest Fuel Assessment





# **Forest Attributes and Terrain Layer Data Stack**

Bare Earth DEM

Hillshade DEM

Drainage Network

Forest Delineated

Forest Delineated Area

Canopy Height Model (C

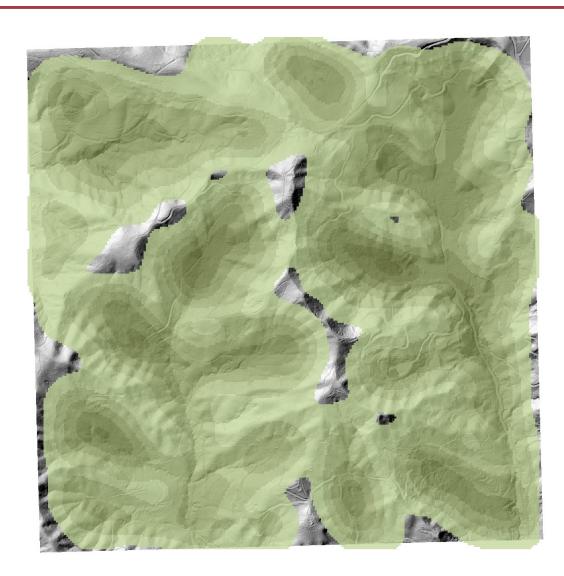
Crown Area

Tree Top

Tree Top Density (Hectare <1,2,3,4,5,6>)

**CHM Tree Top** 

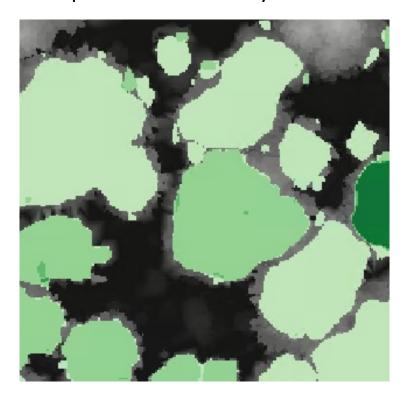
CHM, Tree Top, Crown Ar



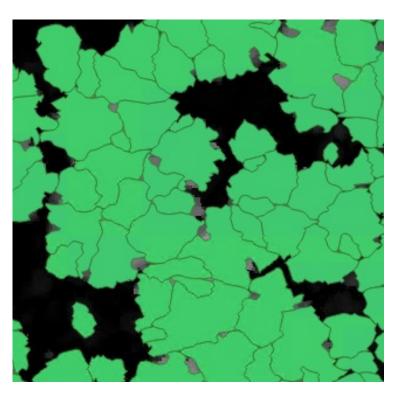


# **Vision Transformer Deep Learning Models**

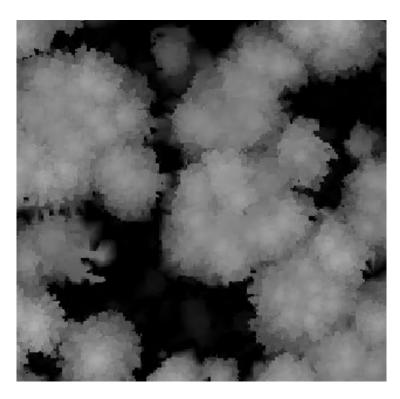
Vision Transformer DLMs are the state-of-art for image recognition in computer vision tasks due rate of accuracy and computational efficiency



Vision Transformer (ViT) Model



Watershed Segmentation

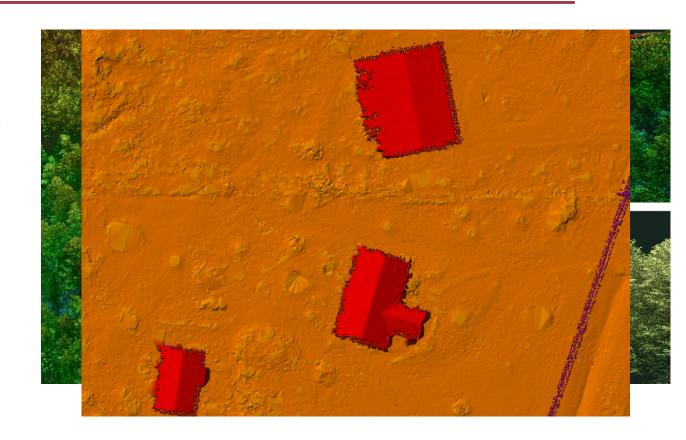


Canopy Height Model

# **Summary**

Geiger Mode LiDAR data bring to the geospatial community the following:

- Powerful technology for building foundation data for Digital Twinning initiative in any environment
- Accurate data to build confidence in 3D models and knowledge content
- Rapid wide area collection, with high-definition and uniform data, to identify fine features
- Multi-look, oblique angles enables superior foliage penetration and 360-degree capture of structures
- Narrow pixel size for penetrating through tree gaps to identify structures and ground measurements



# World Geospatial Forum - Rotterdam, Netherlands 2023

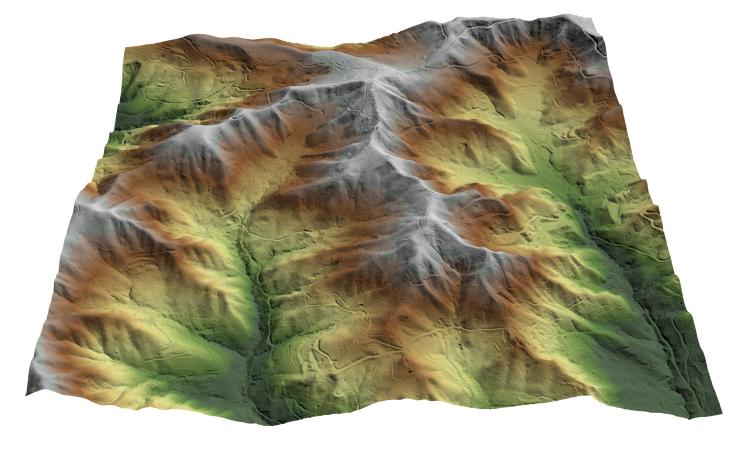
#### Steven McArdle Chief Innovation Officer (smcardle@veridaas.com)

Jian Yang Remote Sensing Specialist
Lamiae El Mendili Artificial Intelligence Specialist

Yasmin Khayer Geospatial Data Engineer
Hans Lie-Nielsen Remote Sensing Specialist
Aleksey Naumov Environmental Scientist

VeriDaaS Corporation
Denver - Calgary - Toronto - Bangalore

Application of Geiger Mode
LiDAR Technology for Extracting
Forest Attributes and Terrain
Mapping



**Questions** 

